

Fig. 5 Variation of optimum tip twist angle/angle-of-attack ratio with  $\beta AR$ .

attack ratio, which produces minimum induced drag for a particular wing, is defined as  $(\epsilon_T/\alpha)_{OPT}$ . Although this optimum cannot be defined with great precision (because of curve fits within the computer program used to calculate wing efficiency), the variation near the optimum is small, so that slight uncertainties will probably not be important for most practical applications. Figure 5 shows the variation of  $(\epsilon_T/\alpha)_{OPT}$  with  $\beta AR$  for twisted, trapezoidal planform wings with taper ratios of 0.2, 0.3, and 0.4.

To design a wing of given planform to have a specified  $C_{LD}$  and minimum induced drag, values of  $\alpha_L$ ,  $\epsilon_T$ , and  $\alpha_0$  must be known. These can be determined as follows:

$$\alpha_L = C_{LD}/C_{L\alpha} \quad (3)$$

where  $C_{L\alpha}$  is obtained from Fig. 1;

$$\epsilon_T = \alpha_L(\epsilon_T/\alpha)_{OPT}/[1 + \alpha_0(\epsilon_T/\alpha)_{OPT}] \quad (4)$$

where  $\alpha_0$  and  $(\epsilon_T/\alpha)_{OPT}$  are obtained from Figs. 2 and 5, respectively; and

$$\alpha_0 = -(\alpha_0)\epsilon_T \quad (5)$$

Thus all quantities needed for wing design are determined.

This note provides information that can be used to estimate rapidly the complete wing aerodynamic characteristics for any uncambered, flat-plate trapezoidal planform wing at subsonic Mach numbers including the linear-lofted twist needed to produce minimum induced drag for a specified lift coefficient. Data obtained from this procedure provide a good starting point for detailed consideration of more complex wing configurations.

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## Rolling Moment Due to Sideslip of Delta Wings

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#### Nomenclature

$C_L$	= lift coefficient
$C_l$	= rolling moment coefficient
$\beta$	= angle of sideslip, rad
$\Lambda$	= angle of sweepback, deg
$\Gamma$	= dihedral angle, deg
$C_{l\beta}$	= $\partial C_l / \partial \beta _{\beta=0}$
$(\partial C_{l\beta} / \partial C_L)_0$	= $\partial C_{l\beta} / \partial C_L _{C_L=0}$
$(\partial C_{l\beta} / \partial C_L)_A$	= contribution of aspect ratio to $(\partial C_{l\beta} / \partial C_L)_0$
$(\partial C_{l\beta} / \partial C_L)_\Lambda$	= contribution of sweepback to $(\partial C_{l\beta} / \partial C_L)_0$
$A$	= aspect ratio

AN extensive literature survey has been conducted to correlate existing experimental data with various predictions of the rolling moment due to sideslip for delta wings.

For incompressible flow the rolling moment due to sideslip for an isolated wing is given by the equation

$$C_{l\beta} = C_L \left[ \left( \frac{\partial C_{l\beta}}{\partial C_L} \right)_A + \left( \frac{\partial C_{l\beta}}{\partial C_L} \right)_\Lambda \right] + \Gamma \left( \frac{\partial C_{l\beta}}{\partial \Gamma} \right)$$

The portion of  $C_{l\beta}$  which is a linear function of lift coefficient is composed of two terms. The first term,  $(\partial C_{l\beta} / \partial C_L)_A$ , which is a function of aspect ratio and taper ratio, arises from two sources: the mutual induction of the leading and trailing wing panels, and the windward wing tip, which becomes effectively a leading edge with high negative pressures at the wing tip. The second term,  $(\partial C_{l\beta} / \partial C_L)_\Lambda$ , is the contribution of sweepback to  $(\partial C_{l\beta} / \partial C_L)_0$ . This contribution to rolling moment arises entirely from the difference in effective sweep angle and aspect ratio of the leading and trailing wing panels in sideslip.

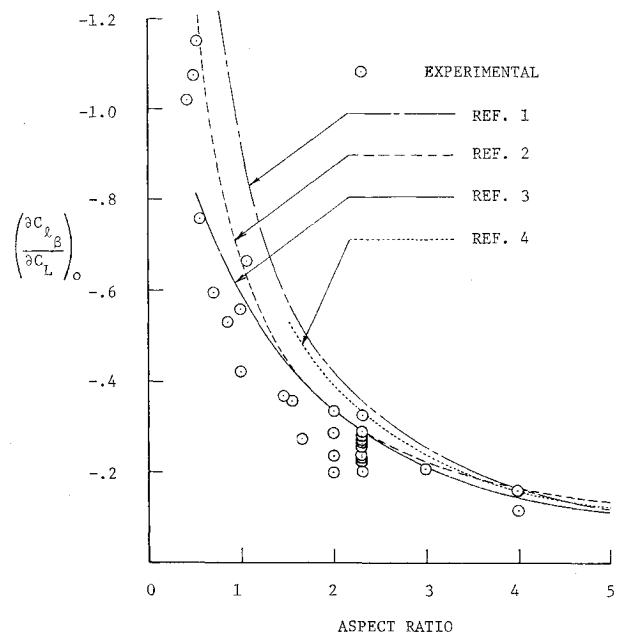


Fig. 1 Experimental and predicted values of  $(\partial C_{l\beta} / \partial C_L)_0$  for delta wings.

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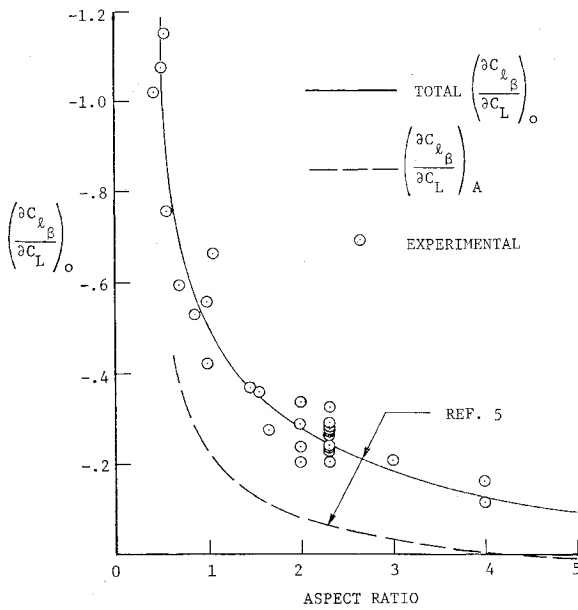


Fig. 2 Prediction for  $(\partial C_{l\beta}/\partial C_L)_0$  for delta wings.

Figure 1 presents the data from a wide variety of experimental studies compared with the predictions resulting from the methods of four primary sources.<sup>1-4</sup> Clearly, all of the methods predict somewhat higher negative values of  $(\partial C_{l\beta}/\partial C_L)_0$  than is justified by the average values of the experimental data points. Table 1 summarizes all of the experimental data.

A recent investigation by the author<sup>5</sup> includes the curve shown in Fig. 2 for predicting  $(\partial C_{l\beta}/\partial C_L)_0$  for delta wings, which agrees quite well with the experimental data. The

Table 1 Summary of delta wing experimental data

Reference	A	$-(\partial C_{l\beta}/\partial C_L)_0$ experimental
6	2.31	0.271
7	2.31	0.232
8	0.50	1.073
8	1.0	0.555
8	2.0	0.200
9	2.31	0.266
10	2.31	0.20
11	1.56	0.356
12	2.0	0.334
13	2.31	0.225
14	2.0	0.236
15	2.31	0.280
16	2.31	0.289
17	2.31	0.325
18	2.0	0.287
19	0.25	2.29
19	0.53	1.15
19	1.07	0.665
19	2.31	0.235
19	4.0	0.1145
19	6.93	0.573
20	3.0	0.206
21	0.42	1.02
21	0.56	0.757
21	0.71	0.595
21	0.85	0.528
21	1.00	0.420
21	1.46	0.367
22	2.31	0.286
22	4.0	0.16
23	1.66	0.272
24	2.31	0.254

curve for  $(\partial C_{l\beta}/\partial C_L)_A$  is included to show the relative effect of aspect ratio and sweepback.

One should note that  $C_{l\beta}$  is a linear function of  $C_L$  only for low to medium lift coefficients for delta wings. The foregoing data apply only to the linear range. The derivative  $(\partial C_{l\beta}/\partial C_L)_0$  was measured at  $C_L = 0$ .

There is presently no satisfactory empirical or theoretical method for predicting  $C_{l\beta}$  in the nonlinear range. For delta wings, the nonlinear effects usually become significant at approximately  $C_L = 0.5C_{L_{max}}$ .

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## A Useful Method of Airfoil Stall Prediction

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### Introduction

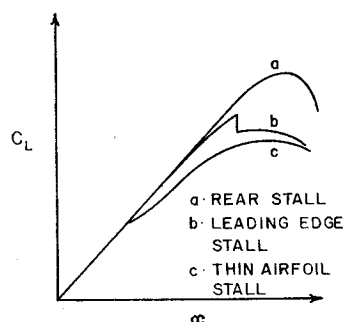
SYSTEMATIC investigations of airfoil stalling characteristics and their relation to the state of the boundary layer began with B. Melvill Jones in the mid 1930's. Jones<sup>1,2</sup> made what is probably the first generalization of stalling characteristics by classifying them into three types: a trailing-edge stall and two types of leading-edge stall. He postulated that stall could result from flow separation at the leading edge as well as the trailing edge, and observed the now well-known "bubble" or localized laminar flow separation.

Subsequent investigators explored the boundary layer and systematically varied the many parameters influencing the mechanism of transition and separation until the three principal types of stall, for which typical lift curves appear in Fig. 1, are now widely accepted: 1) trailing-edge stall, where there is a gradual loss of lift at high lift coefficient as the turbulent separation point moves forward from the trailing edge; 2) leading-edge stall, where there is an abrupt loss of lift, as the angle of attack for maximum lift is exceeded, with little or no rounding over of the lift curves; 3) thin-airfoil stall, where there is a gradual loss of lift at low lift coefficients as the turbulent reattachment point moves rearward.

### Types of Stall

The top curve of Fig. 1 represents the lift variation on a typical rear-stalling airfoil. The Reynolds number is high

Fig. 1 Typical stalling curves.



enough that transition from a laminar to a turbulent boundary layer occurs before laminar separation can occur. Crabtree<sup>3,4</sup> has given, as an empirical condition for such a flow to exist, that the Reynolds number based upon the boundary-layer displacement thickness at separation be greater than 2700,  $(R_{\delta^*})_s > 2700$ . The first separation of the flow is then a turbulent one somewhere on the rear of the section.

The flows associated with leading-edge stall and thin-airfoil stall are characterized by the accompanying bubble, and typical lift curves appear as the center and lower curves, respectively, of Fig. 1. The laminar-separation bubble is characterized by a tangential separation from the airfoil surface with transition at maximum bubble height and the resulting turbulence spreading so that the flow reattaches. The velocity profiles in the separated layer up to transition are characteristic of those for laminar flow. Further downstream they are distorted by the transition process, and shortly after reattachment the profiles are typical of turbulent boundary layers. The static pressure within the bubble is nearly constant from the point of separation to the point of transition and then increases rapidly to the point of reattachment.

Owen and Klanfer<sup>5</sup> have classified bubbles as short if their length is of the order of 100 displacement thicknesses at separation, and long if their length is of the order of 10,000 displacement thicknesses at separation. They also determined a displacement thickness Reynolds number below which only long bubbles form and above which only short bubbles form. This value is between 400 and 500. Crabtree<sup>6</sup> more specifically has found the critical value to be between 400 and 450 when the calculation is based upon experimental pressure distributions and between 450 and 550 when based upon theoretical pressure distribution of potential flow.

The short bubble has a small effect on the over-all pressure distribution, and therefore lift and drag, as long as it reattaches. The long bubble, however, causes a collapse of the leading-edge suction with corresponding loss of lift and increase of drag.

Several criteria exist for the prediction of the laminar separation point. Curle and Skan suggest a form parameter  $H = \delta^*/\theta$ , where  $\theta$  is the boundary-layer momentum thickness, exceeding 3.55.

Crabtree observed that there cannot be laminar reattachment at the rear of a bubble. There must be a considerable widening of the streamlines over the rear portion, and this necessitates a turbulent process. There are two principal mechanisms by which transition can occur in the boundary layer.

Tollmien-Schlichting waves are small, regular oscillations in the laminar boundary layer, not associated with freestream turbulence. These waves can amplify at their natural frequency of oscillation resulting in widespread turbulence. Schubauer and Skramstad<sup>7</sup> have determined a Reynolds number below which the boundary layer is stable for regular disturbances of any wave number.

Turbulent spots occur in a random manner near the upstream limit of the transition region. They spread laterally as wedges and are swept downstream at a velocity less than freestream. New spots are prevented from forming in the downstream region by the enhanced stability of the fluid between the growing turbulent wedges.

The turbulent spot process occurs only when  $(R_{\delta^*})_s$  is greater than about 450 and takes place in a lesser length than that for amplification of waves. This has led to the general opinion that transition by the growth of turbulent spots occurs on short bubbles. On long bubbles  $(R_{\delta^*})_s$  is usually less than 450, and they will not, in general, support the turbulent spot process. Transition is due to amplification of Tollmien-Schlichting waves.

The exact process and parameters involved in the breakdown of short bubbles are still a matter of some controversy, but it is generally agreed that there are two mechanisms for the process. Crabtree has postulated that bursting will occur